


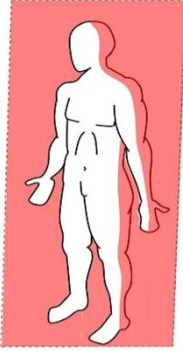
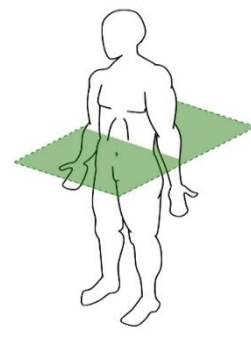
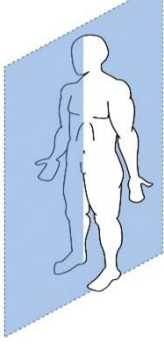


Levers – a rigid bar that moves around a pivot point with force applied to it.

Fulcrum (F)	Effort (E)	Load (L)
A fixed pivot point 	The source of energy that will be applied 	The weight/resistance to be moved 

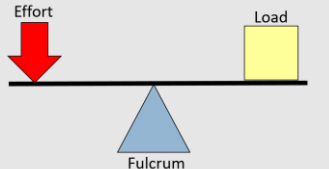
Planes – imagery lines that divide the body into two.

Frontal plane	Transverse plane	Sagittal plane
A vertical plane but this divides the body into front and back e.g. jumping jacks 	A horizontal plane that divides the body into upper and lower halves e.g. bowling in cricket 	A vertical plane that divides the body into right and left sides e.g. kicking, running 


Classes of lever

First class lever:

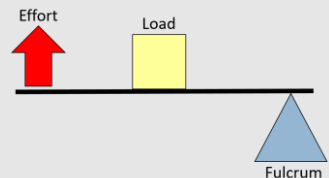

Drawing



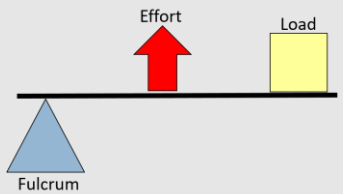

Example



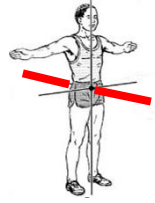

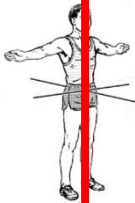

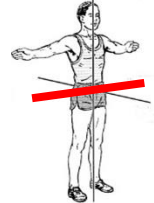

Second class lever:

Third class lever:

Axes – imagery lines that the whole body turns around.

Frontal axis	Longitudinal axis	Transverse axis
Runs through the body horizontally from the back to front.  Example: Cartwheel 	Runs through the body vertically from the top to bottom.  Example: Full twist 	Runs through the body horizontally from the left to right.  Example: Somersault 

Mechanical advantage –

MA = Load / Effort

This is where a lever's **effort arm** is greater than its **load arm**.




Mechanical disadvantage

This is where a lever's **load arm** is longer than its **effort arm**.




Large loads (LA) can be moved with limited effort.

